CLAIMS:

1.   An electric apparatus comprising:
-        sensor means (18) for detecting objects (34, 36) in the proximity of the
apparatus (10), and
-        a directional pointing unit (20) which can be directed onto objects (34, 36) in
5   the proximity of the apparatus (10).

2.   An apparatus as claimed in claim 1, comprising:
-        at least one memory (M) for storing the position (α, β) of objects (34, 36).

10   3.   An apparatus as claimed in any one of the preceding claims, wherein
-        the pointing unit comprises a mechanical pointing element which is
mechanically movable in such a way that it can be directed onto objects in the proximity of
the apparatus.

15   4.   An apparatus as claimed in any one of the preceding claims, wherein
-        the pointing unit (20) comprises a light source for generating a concentrated
light beam (40), and
-        means for directing the light beam (40) onto objects (34, 36) in the proximity
of the apparatus (10).
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5.   An apparatus as claimed in claim 4, wherein
-        the light source is mechanically movable.

6.   An apparatus as claimed in claim 4 or 5, wherein
25   -   means for directing the light beam (40) comprise one or more mechanically
movable mirrors.

7.   An apparatus as claimed in any one of the preceding claims, comprising
-        a personification element (14) having a front side (16),

motion means for mechanically moving the personification element (14),

means for determining the position of a user, and

control means which are constituted in such a way that they control the motion means in such a way that the front side (16) of the personification element (14) is directed towards the user's position.

8.   An apparatus as claimed in claim 7, wherein

the pointing unit (20) is arranged on the personification element (14).

9.   An apparatus as claimed in any one of the preceding claims, comprising

means for speech recognition and speech output.

10.   A method of communication between an apparatus (10) and a user, wherein

the apparatus (10) detects objects (34, 36) in its proximity by way of sensor means (18), and

stores the position of objects (34, 36) in a memory (M), and aligns a directional pointing unit (10) with one of the objects (36).